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Smart City Air Pollution Services from IOT Data Network C. Badii, S. Bilotta, D. Cenni, A. Difino, P. Nesi, I. Paoli, M. Paolucci

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6th Italian Conference on ICT for Smart Cities and Communities

23-25 September, 2020 | University of Salerno - Fisciano (SA), Italy | Virtual Conference







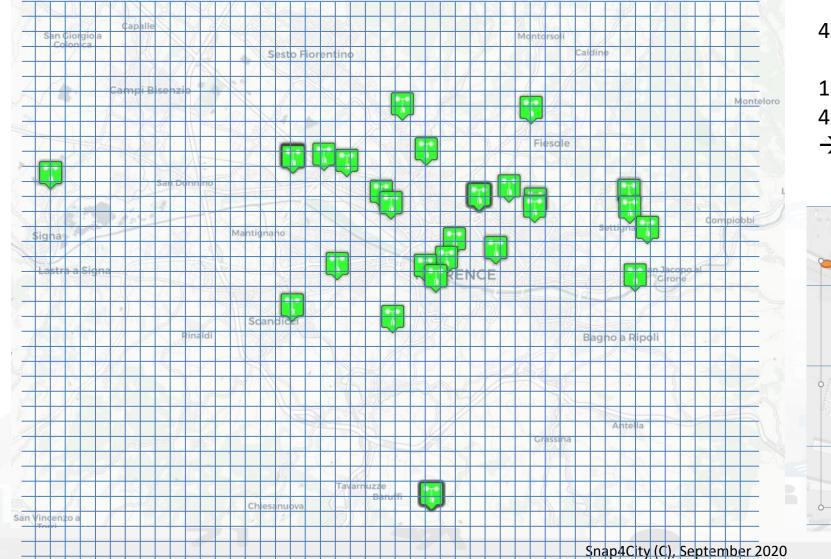


- Air Quality sensors are
 - Collected on scattered positions
- AirQuality Services
 - AirQuality indicators independent on the sensors' position, in any GPS position of the area
 - Multiple data: PM_{10} , $PM_{2.5}$, CO, CO_2 , SO_2 , O_3 , H_2 S, NO, NO_2 , NO_x , air temperature, air humidity, velocity of wind speed, dew point, etc.
- Applications
 - Alerting on specific personal GPS locations
 - Constrained routing for: runners, walking with baby, people with pulmonary problems,
 - Control Room Rendering
 - Mobile Phone Rendering, this means to have thousands of users active at the same time, and a reasonable memory consumption in the server.





The GRID density is never enough



4x4 meters grid is really too expensive

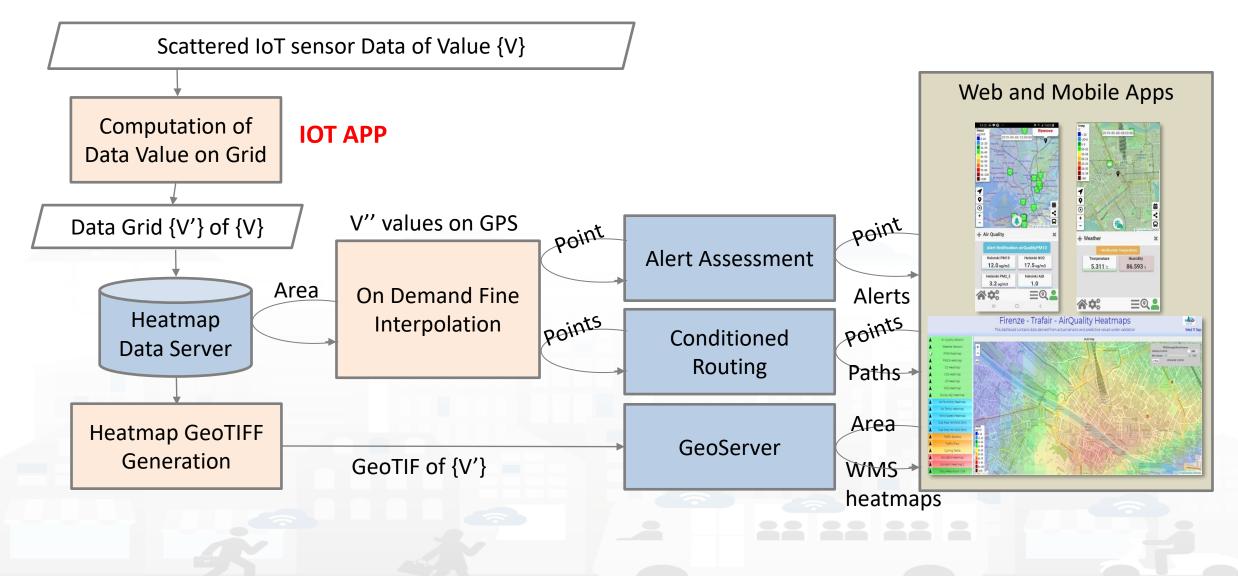
1000x1000 area (small town) 4x4mt * 10 variables * 24 hours per day → 3.8 Billions of data



















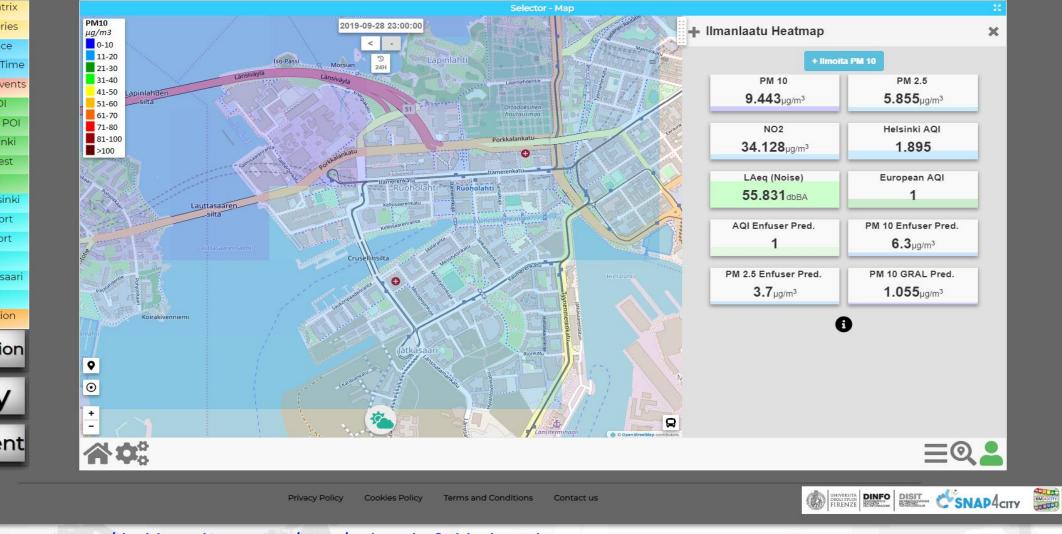


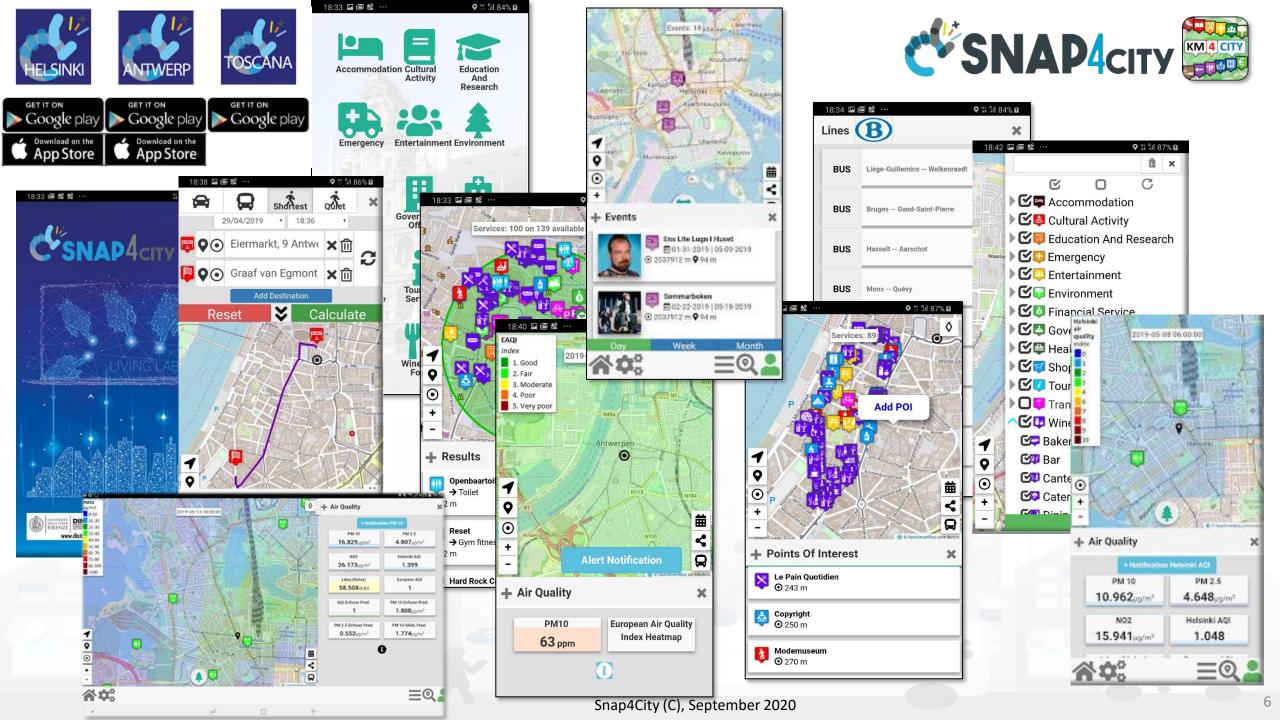


Please note that the data results are not always based on real data.

Sun 29 Sep 00:42:50

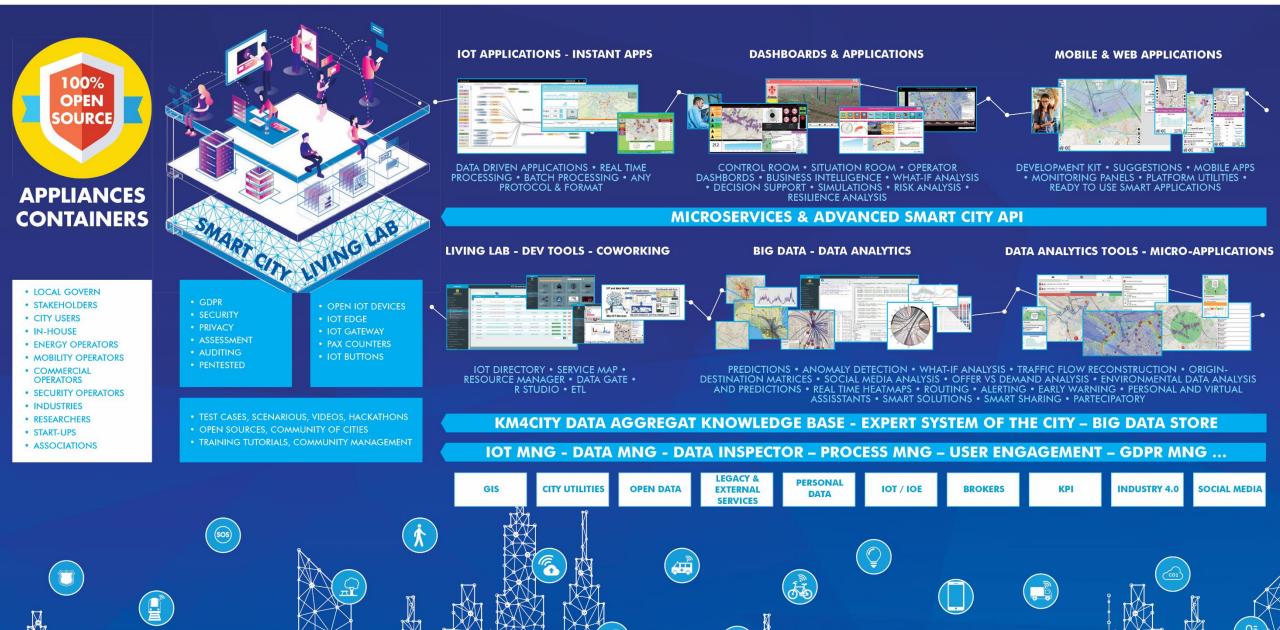








URBAN PLATFORM: SMART CITY IOT AS A SERVICE AND ON PREMISE

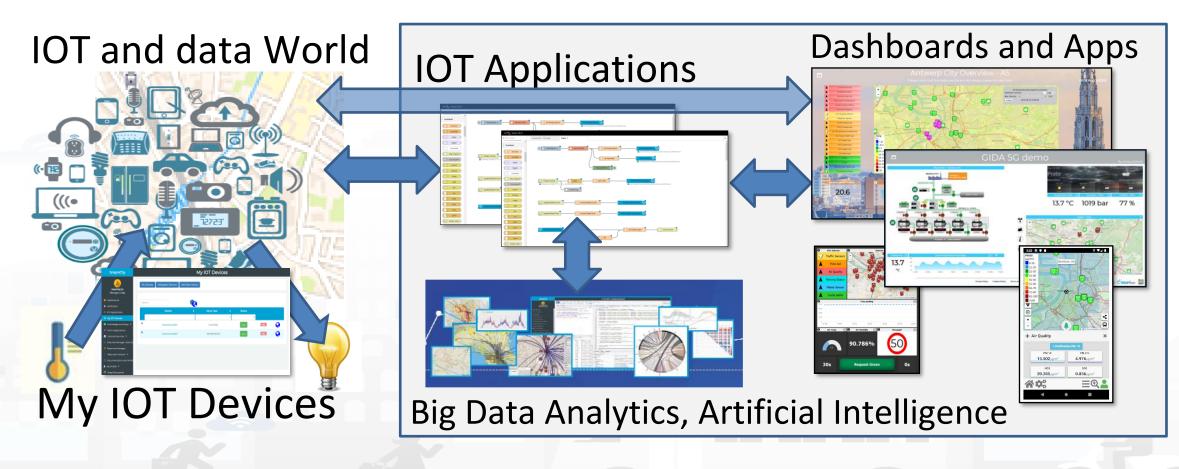






Snap4City: Builder of Sentient Cities Solutions

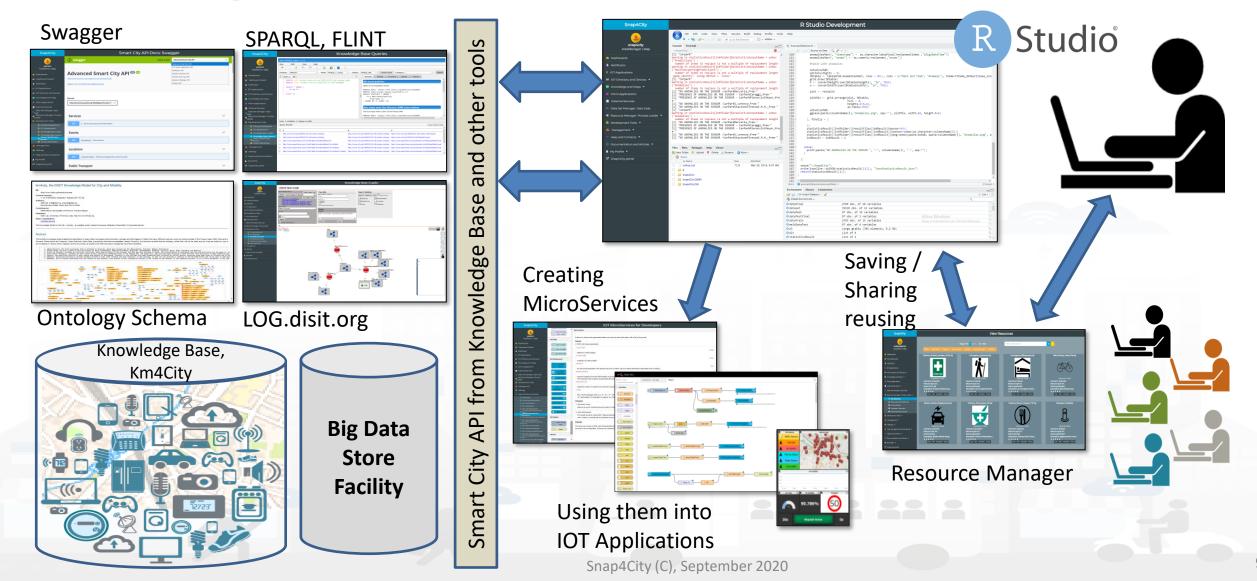
Dashboards with data driven IOT Applications enforcing intelligence







Data Analytics Dev. in R Studio and/or Tensor Flow

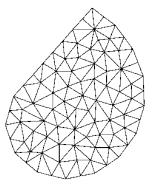






Bivariate Interpolation Method [Akima]

- Steps for irregular data
 - *triangulation* (i.e., partitioning of the area into a number of triangles) of the *x-y* plane
 - *selection* of several data points that are closest to each data point (sensor) and are used for estimating the partial derivatives;
 - *organization* of the resulting data with respect to triangle numbers;
 - estimation of partial derivatives at each data point;
 - computation of the interpolation at each output point.

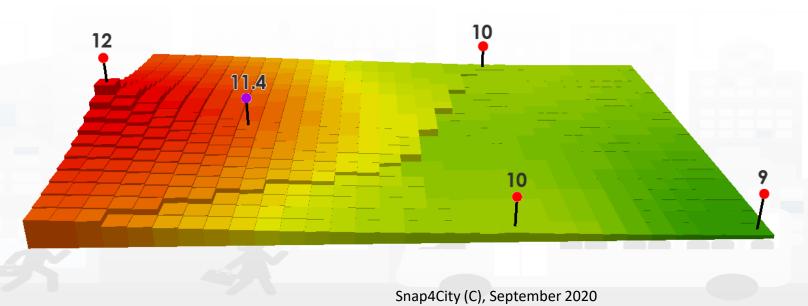






Inverse Distance Weighting, IDW Method

- It is a deterministic mathematical method widely used in the geoscience.
 - the interpolated value at the location (x, y); z_i is the observed value; d_i is the Euclidean distance between the point i and the interpolated point; and w_i is the weight for the point each point (x_i, y_i) and (x, y)







Validation via Error Estimation

 alternate exclusion of selected air quality sensor in contributing to the model and using the excluded as true value for validation in that point on the basis of the estimation performed exploiting all the others.

ers.	Error Measures	Akima	IDW
	MAPE	0.69	0.79
	RMSE	8.90	12.20
	MAPE-we	0.60	0.95
	MAPE-wd	0.70	0.93
	RMSE-we	8.60	10.70
	RMSE-wd	9.70	17.00

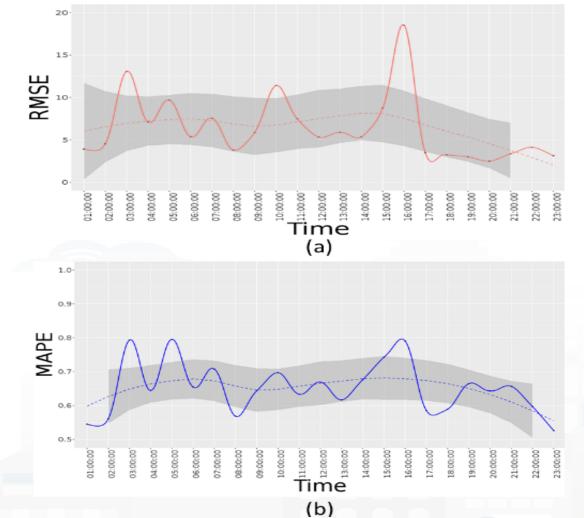
mean absolute percentage error (MAPE)

root mean squared error (RMSE)

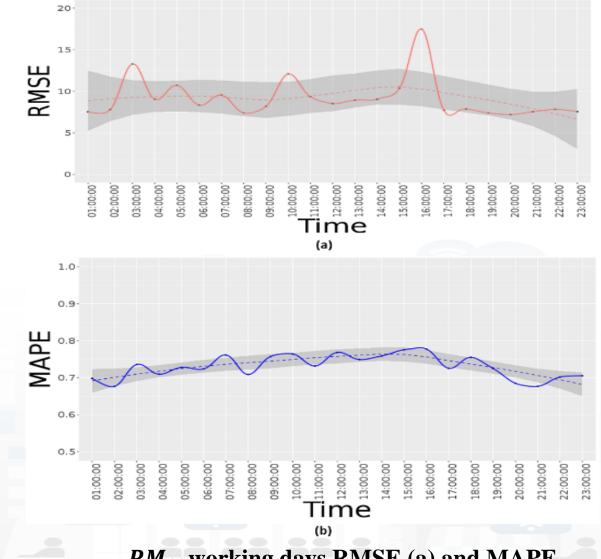








*PM*₁₀working days RMSE (a) and MAPE (b) per time slots (Akima Method)



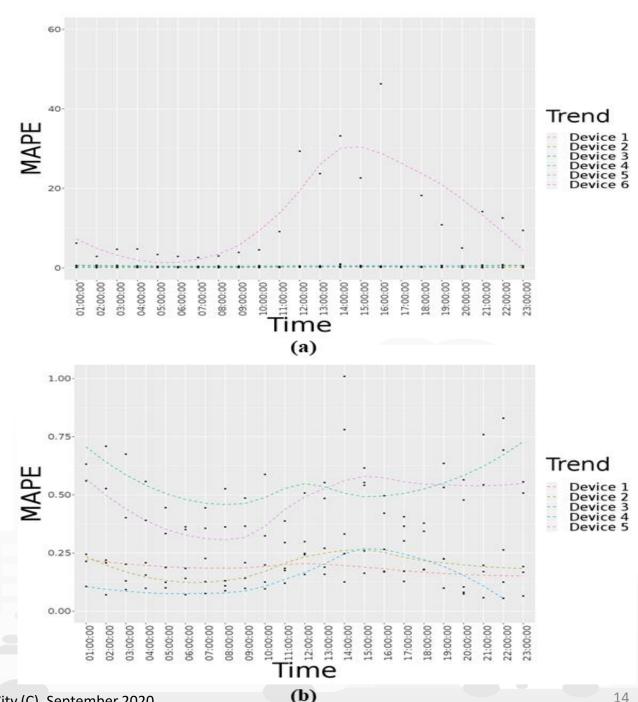
PM₁₀working days RMSE (a) and MAPE (b) per time slots (IDW Method)

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Detecting dysfunction on devices using error detection

- Air Quality PM_{10} working days interpolation error trends per hour in terms of mean absolute percentage error for
 - (a) six personal devices including the device with a dysfunction;
 - (b) five personal devices



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- In order to **satisfy the requirements** reported above:
 - Provide Sensor value in any GPS point, for implementing alerts and other applications (routing), rendering on mobile and control room web pages
- What:
 - Two methods have been implemented
 - A scalable architecture has been defined and implemented to provide these services to several thousands of users
- The selection of the best method has been performed on the basis of and error assessment in which Akima solution has been better ranked.
- The Solution can be also used for detecting eventual dysfunctions of specific IOT Devices in the same area, for example for bad positioning, turned off, etc.